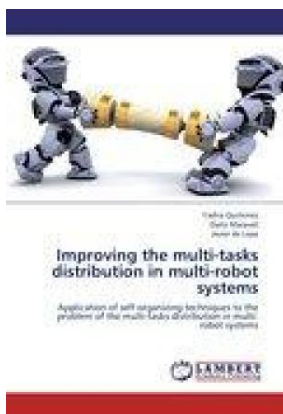


Get eBook

## IMPROVING THE MULTI-TASKS DISTRIBUTION IN MULTI-ROBOT SYSTEMS



LAP Lambert Academic Publishing Jun 2013, 2013. Taschenbuch. Book Condition: Neu. 220x150x8 mm. This item is printed on demand - Print on Demand Neuware - This work study the coordination of multi-robot systems, in particular, addresses the problem of the distribution of heterogeneous multi-tasks. The main interest in these systems is to understand how from simple rules inspired by the division of labor in social insects, a group of robots can perform tasks in an organized and coordinated way. We...

**Download PDF Improving the multi-tasks distribution in multi-robot systems**

- Authored by Yadira Quiñonez
- Released at 2013



Filesize: 7.03 MB

### Reviews

---

*This book can be worthy of a read, and much better than other. It usually fails to charge a lot of. I realized this publication from my dad and i encouraged this pdf to understand.*

-- **Prof. Flo Cruickshank DDS**

*Complete guideline for publication fanatics. It is actually writter in straightforward words rather than confusing. I am effortlessly could get a pleasure of looking at a written book.*

-- **Kirstin Schuppe**

*If you need to adding benefit, a must buy book. it was writtern really perfectly and beneficial. You may like the way the author create this ebook.*

-- **Rebekah Becker**

---